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The 27th Annual  
ARRL and TAPR Digital Communications Conference

September 26-28, 2008 - Chicago, Illinois



## WINMOR...A Sound Card ARQ Mode for Winlink HF Digital Messaging

Rick Muething, KN6KB, AAA9WK  
Winlink Development Team  
6143 Anchor Lane  
Rockledge, FL 32955  
[rmuething@cfl.rr.com](mailto:rmuething@cfl.rr.com)

### Abstract:

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Rick Muething, KN6KB

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aktuell	12:04, 9. Okt. 2009		1.275 × 1.650, 8	Anonym (Diskussion   Beiträge)	Erste WINMOR Präsentation anlässlich der 27. ARRL & TAPR Digital Communications Conference Sept. 2008 in Chicago, Rick Muething, ARRL and TAPR Digital Communications Conference September 26-28, 2008 - Chicago, Illinois



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### Dateiverwendung

Rick Muething, KN6KB, AAA9WK  
Winlink Development Team

Die folgende Seite verwendet diese Datei  
 6143 Anchor Lane  
 Dade College, FL 32955  
[rmuething@cfl.rr.com](mailto:rmuething@cfl.rr.com)

- WINMOR

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#### Umwandlungsprogramm

Mac OS

#### Verschlüsselt

no

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1,3

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## Amateurfunkfreund



Name            Amateurfunkfreund

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## Anonym

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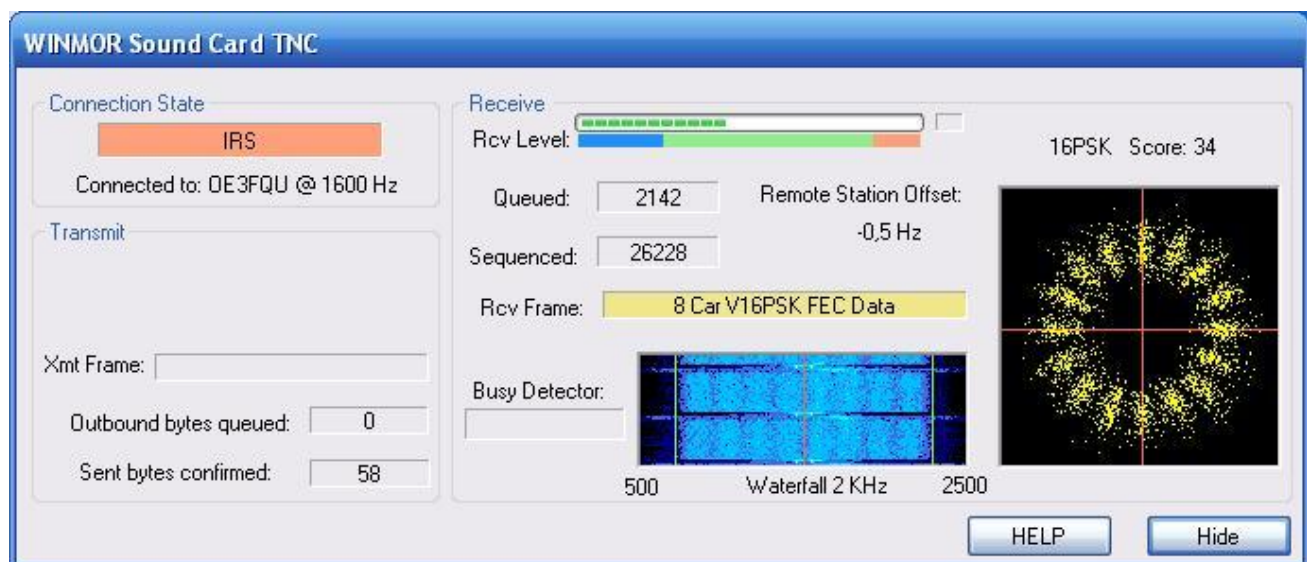


# WINMOR

**ACHTUNG: WINMOR wurde mit Ende 2020 außer Betrieb genommen! Ersatz sind entweder ARDOP oder VARA!**

**Dieser Artikel bleibt zum Nachlesen noch erhalten!**

## WINMOR (Winlink Message over Radio) - ein Soundkarten TNC



WINMOR-Mode im 80m QRM mit 1600 Hz Bandbreite, 8 Träger, 16PSK, FEC - Datendurchsatz etwa 5000 Zeichen pro Minute

### Inhaltsverzeichnis

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## Allgemeines

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WINMOR wurde als digitales ARQ Übertragungsprotokoll [1] für die Verwendung mit dem Winlink2000 (WL2K) [2] Netzwerk konzipiert. Mit WINMOR entfällt die Notwendigkeit kostspieliger, externer, PACTOR Modem-Hardware. Allerdings wird WINMOR kaum die Leistungsfähigkeit von PACTOR 3 oder PACTOR 4 bez. Datendurchsatz und Betriebssicherheit erreichen können. WINMOR wurde auf der ARRL/TAPR Digital Communications Conference in Chicago, September 26-28, 2008 erstmals präsentiert.

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WINMOR ist keine Software, sondern ein Protokoll, es gibt zur Zeit zwei Programme, die dieses Protokoll verwenden:

- **RMS Express** ein Benutzer-Client-Programm
- **RMS Winmor**, ein Radio-Message-Server als Teil des WL2K Systems.

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## Protokollbeschreibung

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Die Protokollbeschreibung (englisch)

### WINMOR Protocol Specification (Preliminary)

Revision: 1.0.0 Oct 13, 2009

Rick Muething, KN6KB, AAA9WK

#### 1.0 Scope:

This document describes the preliminary WINMOR sound card protocol at the physical and data link levels. It is the complete specification of the WINMOR protocol. It does not address higher level protocol layers. The WINMOR protocol is not proprietary and is released to the public domain. This document describes the 500 Hz and 1600 Hz bandwidth modes using 93.75 Baud (PSK) and 46.875 baud FSK modulation.

#### 2.0 Purpose:

The intent of this document is two fold:

- a) To serve as a working document during protocol development and testing
- b) To serve as a template to allow others familiar with the art to build compatible drivers that support the data link protocol layer.

#### 3.0 Definitions and Syntax:

Several specific terms and syntax are used in this document:

Definitions: A term or item is defined using the := symbol. This symbol can be read as "is defined as"

Implementation directives: These are key words that indicate how an item is to be implemented or recommend a method of implementation. They are always indicated by capitalized italic words. These are:

*MUST* := this must be followed to implement the protocol

*MUST NOT* := this must not be done to implement the protocol

*SHOULD* := this is the recommended way to implement the protocol

*MAY* := this is alternative way to implement the protocol.

The syntax above is always used to distinguish between the common use of the same words.

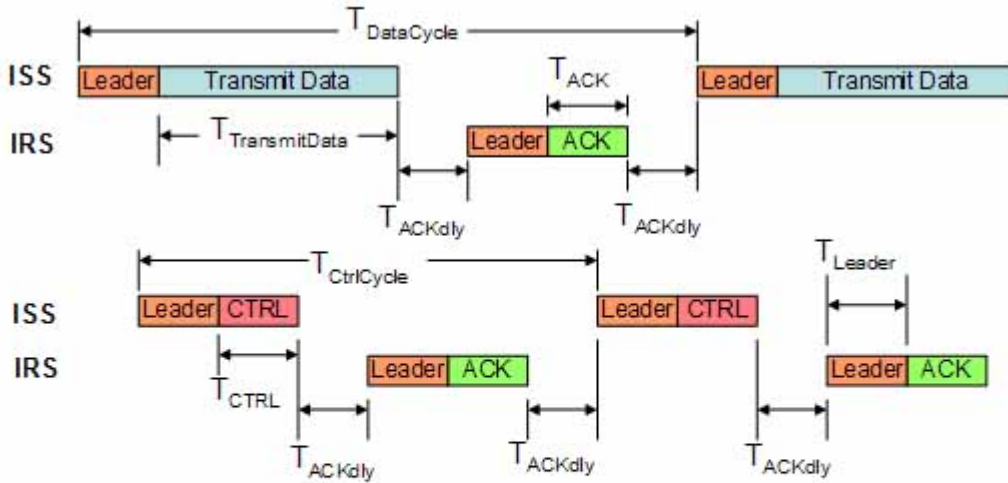
& is used to indicate catenation. E.g. Frame := Pilot & Data

#### 4.0 Overview of the Protocol:

The WINMOR protocol is intended to be used for sending messages and binary data error free over a HF radio link. It is a Selective Repeat Automatic Retry reQuest (SRARQ) protocol where the Information Receiving Station (IRS) acknowledges receipt of the data to the Information Sending Station (ISS). Normally during a connection session the IRS and ISS exchange roles multiple times. The protocol is designed to handle the type conditions normally encountered in amateur radio transmission.

## Winmor Timing

Frame Timing Details for ISS and IRS (not to scale)



- $T_{leader}$  28 Symbols + optional 12 symbol VOX extension (298.6 – 426.6 ms)
- $T_{ACKdly}$  100ms Min, 500 ms max
- $T_{DataCycle}$  Repeat interval if NO ACK received  $\geq T_{TransmitData} + T_{ACK} + 2(T_{Leader} + T_{ACKdly})_{max}$
- $T_{CtrlCycle}$  Repeat interval if NO ACK received  $\geq T_{CTRL} + T_{ACK} + 2(T_{Leader} + T_{ACKdly})_{max}$

## Durchsatzraten

Tabelle erzielbarer Daten-Durchsatzraten

WINMOR Mode Rate Worksheet (200, 500, 1000, 2000Hz B Revised: 9/17/2009 Rick Muething, KN6KB

Mode Description	Info	Samp/	# of	-BW	Raw	Leader	OH/Car	PL/Car	RS-FEC/	Frame	Frame	Rx+Tx	Tot Cycle	Net max	Throughput			
	b/Sym	Sym	Baud	car	(Hz)	bps/H(Sym)	(Sym)	(sym)	Car	Length	Length	+O	Len	(bits/sec)	(by/min)			
15 Car 16PSK Prag TCM + RS	3	128	62,50	15	2000	1,41	27	16	256	56	355	5,680	1,056	0,3	7,036	1637,3	12280	4093
15 Car 8PSK Prag TCM + RS	2	128	62,50	15	2000	0,94	27	24	256	48	355	5,680	1,056	0,3	7,036	1091,5	8186	2729
15 Car 4PSK Prag TCM + RS	1	128	62,50	15	2000	0,47	27	48	192	80	347	5,552	1,056	0,3	6,908	416,9	3127	1042
15 Car 4FSK +RS	2	256	31,25	15	2000	0,47	13	24	64	64	165	5,280	1,056	0,3	6,636	289,3	2170	723
7 Car 16PSK Prag TCM + RS	3	128	62,50	7	1000	1,31	27	16	256	56	355	5,680	1,056	0,3	7,036	764,1	5731	1910
7 Car 8PSK Prag TCM + RS	2	128	62,50	7	1000	0,88	27	24	256	48	355	5,680	1,056	0,3	7,036	509,4	3820	1273
7 Car 4PSK Prag TCM + RS	1	128	62,50	7	1000	0,44	27	48	192	80	347	5,552	1,056	0,3	6,908	194,6	1459	486
7 Car 4FSK +RS	2	256	31,25	7	1000	0,44	13	24	64	64	165	5,280	1,056	0,3	6,636	135,0	1013	338
3 Car 16PSK Prag TCM + RS	3	128	62,50	3	500	1,13	27	16	256	56	355	5,680	1,056	0,3	7,036	327,5	2456	819
3 Car 8PSK Prag TCM + RS	2	128	62,50	3	500	0,75	27	24	256	48	355	5,680	1,056	0,3	7,036	218,3	1637	546
3 Car 4PSK Prag TCM + RS	1	128	62,50	3	500	0,38	27	48	192	80	347	5,552	1,056	0,3	6,908	83,4	625	208
3 Car 4FSK +RS	2	256	31,25	3	500	0,38	13	24	64	64	165	5,280	1,056	0,3	6,636	57,9	434	145
1 Car 16PSK Prag TCM + RS	3	128	62,50	1	200	0,94	27	16	256	56	355	5,680	1,056	0,3	7,036	109,2	819	273
1 Car 8PSK Prag TCM + RS	2	128	62,50	1	200	0,63	27	24	256	48	355	5,680	1,056	0,3	7,036	72,8	546	182
1 Car 4PSK Prag TCM + RS	1	128	62,50	1	200	0,31	27	48	192	80	347	5,552	1,056	0,3	6,908	27,8	208	68
1 Car 4FSK +RS	2	256	31,25	1	200	0,31	13	24	64	64	165	5,280	1,056	0,3	6,636	19,3	145	48
1 Car Connect Request (V4PSK)+RS	1	128	62,50	1	200	0,31	27	0	104	32	163	2,608						
1 Car Coded Control 4FSK +RS	2	256	31,25	1	200	0,31	13	0	8	8	29	0,928						
1 Car ACK 4FSK +RS	2	256	31,25	1	200	0,31	13	0	12	8	33	1,056						
Leader extension (symbols 0-16)	0				See Note 2													
Calculated Leader extension (ms)	0																	

- Notes:
- 1) The 4FSK mode was modified for lower user data and higher RS FEC and now runs slower than the 4PSK mode.
  - 2) Leader extension up to 16 symbols (256 ms) may be used for slow switchover Transceivers or VOX operated PTT
  - 3) The above modes yield the following speed ranges depending on session bandwidth:  
note these selections may change based on testing!  
2000 Hz BW Sessions: 15x16PSK, 15x8PSK, 15x4PSK, 15x4FSK, 7x4FSK - 12:1 speed range  
1000 Hz BW Sessions: 7x16PSK, 7x8PSK, 7x4PSK, 7x4FSK, 3x4FSK - 13:1 speed range  
500 Hz BW Sessions: 3x16PSK, 3x8PSK, 3x4PSK, 3x4FSK, 1x4FSK - 18:1 speed range  
200 Hz BW Sessions: 1x16PSK, 1x8PSK, 1x4PSK, 1x4FSK - 6:1 speed range
  - 4) Session BW is set by Server (answering) station using one of 4 coded Idle frames (200, 500, 1000, or 2000 Hz)
  - 5) All PSK modes use pragmatic Trellis Code Modulation (one redundancy bit/symbol) and use the standard R=1/2, K=7 (NASA Voyager) Viterbi Encoder/Decoder based on Phil Karns Code.
  - 6) Rx + Tx + O refers to the receive to transmit, transmit to receive and software overhead delays and is typical for modern hardware. The protocol actually measures the latency due to RX-TX switchover, sound card and CPU processing latency.
  - 7) Word per minute calculation based on average word of 5 char + space and a 50% compression ratio (typical using B2 compression on mid to large messages). Short messages will be less.

## Software

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Die Software RMS Express kann von hier heruntergeladen werden > <http://www.winlink.org/ClientSoftware>

Voraussetzungen: WIN-XP oder -Vista, .NET3.5, höherwertige Soundkarte z.B. [3], KW-Transceiver

WINMOR unterstützt direkt den USB-Soundkartentreiber (USB Audio Codec) für die ICOM IC-7200 und IC-7600 KW-Transceiver.

Die Software RMSExpress mit den Betriebsarten WINMOR, Pactor, Packet, Telnet wurde anlässlich der HAMVENTION im Mai 2010 freigegeben.

## RMS Express + Winmor, Beschreibung und Setup, Stand November 2010

gezippte Powerpoint-Präsentation [Datei:Winmor.zip](#)