

## WINMOR

[Versionsgeschichte interaktiv durchsuchen](#)  
[Visuell Wikitext](#)

**Version vom 9. Oktober 2009, 12:05 Uhr**  
**(Quelltext anzeigen)**

Anonym ([Diskussion](#) | [Beiträge](#))  
(→Allgemeines)

[← Zum vorherigen Versionsunterschied](#)

**Version vom 9. Oktober 2009, 12:22 Uhr**  
**(Quelltext anzeigen)**

Anonym ([Diskussion](#) | [Beiträge](#))  
(→Durchsatzraten)

[Zum nächsten Versionsunterschied →](#)

Zeile 20:

== Durchsatzraten ==

== Software ==

Zeile 20:

== Durchsatzraten ==

+

+

**Tabelle erzielbarer Daten-  
Durchsatzraten [[Datei:  
WINMOR\_Rate\_WS.pdf]]**

== Software ==

## Version vom 9. Oktober 2009, 12:22 Uhr

### Soundkarten TNC im Peer-to Peer Betatest

WINMOR Sound Card TNC

Connection State  
IRS  
Connected to: OE3ZK-3 @ 500 Hz

Transmit  
Xmt Frame: ACK: 01C0  
Outbound bytes queued: 0  
Sent bytes confirmed: 61

Receive  
Rcv Level:   
Busy Detector:   
Remote Station Offset: 1,2 Hz  
Queued: 0 Sequenced: 4796  
Rcv Frame:

16PSK Score: 71

Waterfall 2 KHz

HELP Hide

## Inhaltsverzeichnis

1 Allgemeines .....	4
2 Protokollbeschreibung .....	5
3 Durchsatzraten .....	6
4 Software .....	6
5 Betatest- und Sked-Frequenzen .....	6



## Allgemeines

---

WINMOR wurde als digitales ARQ Übertragungsprotokoll [1] für die Verwendung mit dem Winlink2000 (WL2K) [2] Netzwerk konzipiert. Mit WINMOR entfällt die Notwendigkeit kostspieliger, externer, PACTOR Modem-Hardware. Allerdings wird WINMOR nie die Leistungsfähigkeit von PACTOR 3 erreichen können (Datendurchsatz/Betriebsicherheit). WINMOR wurde auf der ARRL/TAPR Digital Communications Conference in Chicago, September 26-28, 2008 erstmals präsentiert.

The 27th Annual  
ARRL and TAPR Digital Communications Conference

September 26-28, 2008 - Chicago, Illinois



## WINMOR...A Sound Card ARQ Mode for Winlink HF Digital Messaging

Rick Muething, KN6KB, AAA9WK  
Winlink Development Team  
6143 Anchor Lane  
Rockledge, FL 32955  
[rmuething@cfl.rr.com](mailto:rmuething@cfl.rr.com)

### Abstract:

The improving computational performance of PCs and the near real-time response of PC operating systems now make it feasible to implement reasonable performance HF ARQ messaging protocols suitable for digital messaging. While Pactor (I, II, III) currently dominate and generally represent the best available performance, PC sound cards with appropriate DSP software can now begin to approach Pactor performance at lower cost than dedicated hardware HF modems. This paper covers the on-going development of an optimized sound card mode WINMOR, compatible with the popular Winlink 2000 message system<sup>1,2,3</sup>. This effort leverages a prior feasibility project by the author in the evaluation of SCAMP<sup>4</sup>, an adaptation of RDFT for digital messaging systems. The paper reviews the development effort of **WINMOR (WINlink Message Over Radio)** from motivation through tool development, programming, testing and deployment in the WL2K system.

### Key Words:

Winlink 2000, WINMOR, ARQ protocols, multi-carrier PSK, Sound Card Modes, Pactor, SCAMP, HF Channel Simulators

### Motivation:

The PC, widely available DSP tools, well designed sound card/radio interfaces and improving amateur software skills have yielded a variety of sound card modes over the last several years. These modes range from simple DSP/software implementation of RTTY through complex streaming applications like Win DRM. It is one of the few remaining areas where amateurs can and do experiment. Many of the modes developed however are a replacement of existing "chat" modes or "broadcast" modes where absolute accuracy is not a requirement or data is limited to plain ASCII text. Today, however, a viable message system (with the need for compression and binary attachments) requires true "error-free" delivery of binary data. To achieve this there must be some "back channel" or *ARQ (Automatic Retry reQuest)* so the receiving station can notify the sender of lost or damaged data and request retransmission or repair. HF Pactor (I, II, III) has served us well in this regard providing good performance (net bits/sec/ Hz bandwidth) and robustness. However the proprietary nature of high performance Pactor modems (Pactor II, III) can be cost prohibitive especially in applications such as emergency communications where wide deployment coupled with low average usage make it difficult to justify the investment in high performance but costly hardware. As developers of Winlink 2000 we are continually asked to supply a lower cost of entry than Pactor for those needing to access the WL2K system on HF.

WINMOR ist keine Software, sondern ein Protokoll, es gibt jetzt zwei Programme in der Entwicklung, die dieses Protokoll verwenden:

- **RMSExpress** ein Benutzer-Client-Programm
- **RMS-HF**, ein Radio-Message-Server als Teil des WL2K Systems.

# Protokollbeschreibung

## Durchsatzraten

Tabelle erzielbarer Daten-Durchsatzraten

\*WINMOR Mode Rate Worksheet (200, 500, 1000, 2000Hz B      Revised: 9/17/2009      Rick Muething, KN6KB

Mode Description	Info b/Sym	Samp/ Sym	Baud	# of -BW car (Hz)	Raw Leader bps/Ht:(Sym)	OH/Car (Sym)	PL/Car (sym)	RS-FEC/ Car (sym)	Frame Length (sym)	Frame Length (sec)	ACK (sec)	Rx+Tx +O (sec)	Tot Cycle Len (sec)	Net max Throughput (bits/sec)	Net max Throughput (wrds/min)			
15 Car 16PSK Prag TCM + RS	3	128	62,50	15	2000	1,41	27	16	256	56	355	5,680	1,056	0,3	7,036	1637,3	12280	4093
15 Car 8PSK Prag TCM + RS	2	128	62,50	15	2000	0,94	27	24	256	48	355	5,680	1,056	0,3	7,036	1091,5	8186	2729
15 Car 4PSK Prag TCM + RS	1	128	62,50	15	2000	0,47	27	48	192	80	347	5,552	1,056	0,3	6,908	416,9	3127	1042
15 Car 4FSK +RS	2	256	31,25	15	2000	0,47	13	24	64	64	165	5,280	1,056	0,3	6,636	289,3	2170	723
7 Car 16PSK Prag TCM + RS	3	128	62,50	7	1000	1,31	27	16	256	56	355	5,680	1,056	0,3	7,036	764,1	5731	1910
7 Car 8PSK Prag TCM + RS	2	128	62,50	7	1000	0,88	27	24	256	48	355	5,680	1,056	0,3	7,036	509,4	3820	1273
7 Car 4PSK Prag TCM + RS	1	128	62,50	7	1000	0,44	27	48	192	80	347	5,552	1,056	0,3	6,908	194,6	1459	486
7 Car 4FSK +RS	2	256	31,25	7	1000	0,44	13	24	64	64	165	5,280	1,056	0,3	6,636	135,0	1013	338
3 Car 16PSK Prag TCM + RS	3	128	62,50	3	500	1,13	27	16	256	56	355	5,680	1,056	0,3	7,036	327,5	2456	819
3 Car 8PSK Prag TCM + RS	2	128	62,50	3	500	0,75	27	24	256	48	355	5,680	1,056	0,3	7,036	218,3	1637	546
3 Car 4PSK Prag TCM + RS	1	128	62,50	3	500	0,38	27	48	192	80	347	5,552	1,056	0,3	6,908	83,4	625	208
3 Car 4FSK +RS	2	256	31,25	3	500	0,38	13	24	64	64	165	5,280	1,056	0,3	6,636	57,9	434	145
1 Car 16PSK Prag TCM + RS	3	128	62,50	1	200	0,94	27	16	256	56	355	5,680	1,056	0,3	7,036	109,2	819	273
1 Car 8PSK Prag TCM + RS	2	128	62,50	1	200	0,63	27	24	256	48	355	5,680	1,056	0,3	7,036	72,8	546	182
1 Car 4PSK Prag TCM + RS	1	128	62,50	1	200	0,31	27	48	192	80	347	5,552	1,056	0,3	6,908	27,8	208	69
1 Car 4FSK +RS	2	256	31,25	1	200	0,31	13	24	64	64	165	5,280	1,056	0,3	6,636	19,3	145	48
1 Car Connect Request (V4PSK) +RS	1	128	62,50	1	200	0,31	27	0	104	32	163	2,608						
1 Car Coded Control 4FSK + RS	2	256	31,25	1	200	0,31	13	0	8	8	29	0,928						
1 Car ACK 4FSK +RS	2	256	31,25	1	200	0,31	13	0	12	8	33	1,056						
Leader extension (symbols 0-16)	0				See Note 2													
Calculated Leader extension (ms)	0																	

- Notes:**
- The 4FSK mode was modified for lower user data and higher RS FEC and now runs slower than the 4PSK mode.
  - Leader extension up to 16 symbols (256 ms) may be used for slow switchover Transceivers or VOX operated PTT
  - The above modes yield the following speed ranges depending on session bandwidth:  
note these selections may change based on testing!  
2000 Hz BW Sessions: 15x16PSK, 15x8PSK, 15x4PSK, 15x4FSK, 7x4FSK - 12:1 speed range  
1000 Hz BW Sessions: 7x16PSK, 7x8PSK, 7x4PSK, 7x4FSK, 3x4FSK - 13:1 speed range  
500 Hz BW Sessions: 3x16PSK, 3x8PSK, 3x4PSK, 3x4FSK, 1x4FSK - 18:1 speed range  
200 Hz BW Sessions: 1x16PSK, 1x8PSK, 1x4PSK, 1x4FSK - 6:1 speed range
  - Session BW is set by Server (answering) station using one of 4 coded Idle frames (200, 500, 1000, or 2000 Hz)
  - All PSK modes use pragmatic Trellis Code Modulation (one redundancy bit/symbol) and use the standard R=1/2, K=7 (NASA Voyager) Viterbi Encoder/Decoder based on Phil Karns Code.
  - Rx + Tx + O refers to the receive to transmit, transmit to receive and software overhead delays and is typical for modern hardware. The protocol actually measures the latency due to RX>TX switchover, sound card and CPU processing latency.
  - Word per minute calculation based on average word of 5 char + space and a 50% compression ratio (typical using B2 compression on mid to large messages). Short messages will be less.

## Software

### Betatest- und Sked-Frequenzen

14.112 MHz Dial USB ist die Hauptfrequenz in Europa für den Betatest

Skeds können hier [\[3\]](#) vereinbart werden.

#### MHeard Log 14.112 MHz

2009.10.08 18:36:56 K2MO

2009.10.08 18:29:01 C56DL

2009.10.08 17:30:01 PD4U

2009.10.06 19:28:10 KB3CS

2009.10.06 18:54:15 N2UBP

2009.10.06 18:53:37 9Y4LT

2009.10.06 18:22:02 K4PPK

2009.10.06 16:23:40 EA5GF

2009.10.05 19:50:52 OE1KBC

2009.10.05 18:07:47 K4DMU

2009.10.05 17:58:52 KD4NUE

2009.10.05 16:31:11 KR4XN

2009.10.05 16:19:57 NY3J

2009.10.05 15:28:28 KB0E

2009.10.05 15:25:33 OH7JJT

2009.10.05 14:26:48 OE3ZK-3

2009.10.04 17:51:26 PA0LSK

2009.10.04 17:34:09 IZ3LEF

2009.10.04 17:30:37 EA2AFR

2009.10.04 14:02:38 K4JCC

2009.10.04 13:05:12 LA3RIA

2009.10.03 18:30:42 9Z4BM

2009.10.03 15:49:00 VE2AEY

2009.10.03 15:26:10 VA3LKI

2009.10.03 14:22:46 W5SEG

2009.10.03 13:50:44 ON5VW

2009.10.03 13:37:45 N1CPE

2009.10.03 12:58:28 LA5VNA

2009.10.03 12:02:13 I3FUE

2009.10.03 09:41:43 S57MK

2009.10.01 18:12:13 LZ1CWK

2009.10.01 17:38:25 LZ1OE

2009.10.01 09:02:31 LZ1ZM

2009.09.29 11:22:49 SM6ESQ